

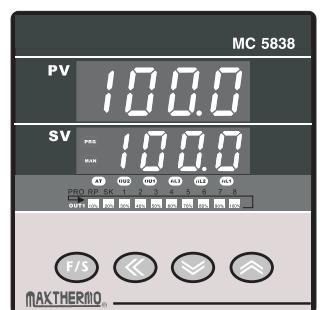
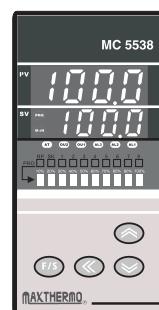
Terwin Instruments Ltd.

Temperature PID Controllers

MC-5x38 OPERATIONAL MANUAL

MAXTHERMO®

MC 5438 / MC 5538 / MC 5638
MC 5738 / MC 5838





Display unit & Indication lamps

PV	=Measured value display
SV	=Set value dispaly
AL1	=Alarm 1 output lamp
AL2	=Alarm 2 output lamp
AL3	=Alarm 3 output lamp
OU1	=Control output 1 lamp
OU2	=Control output 2 lamp
AT	=Autotuning lamp
MAN	=Manual mode lamp
10% ~ 100%	=Manipulated output value display
PRG	=Programmable mode lamp
1~8	=Segment-in-process display lamp
RP	=Ramping mode lamp(programmable mode only)
SK	=Soaking mode lamp (programmable mode only)

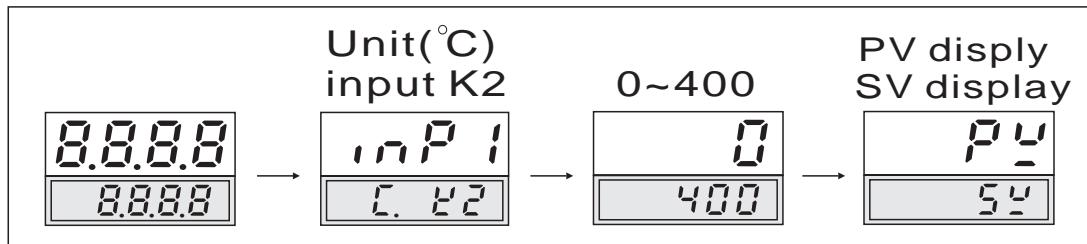
Operation keys

F/S	=Function & Set key
←	=Shift key
↓	=Down key
↑	=Up key
↑	Press 3 sec while the SV is not flashing = Used for returning to initial window
↓	Press 3 sec while in level selection window= Used for calling up lock function
↓	Press 3 sec while in pv/sv initial window= Used for stopping output and SV window will display "HOLD", ↓ press 3 sec again to regain output (This function is available only while OUTM is selected 1 or 2)
F/S	Press 3 sec while in pv/sv initial window= Used for calling up level selection
F/S	Press 3 sec while in level selection window= Used for entering each level

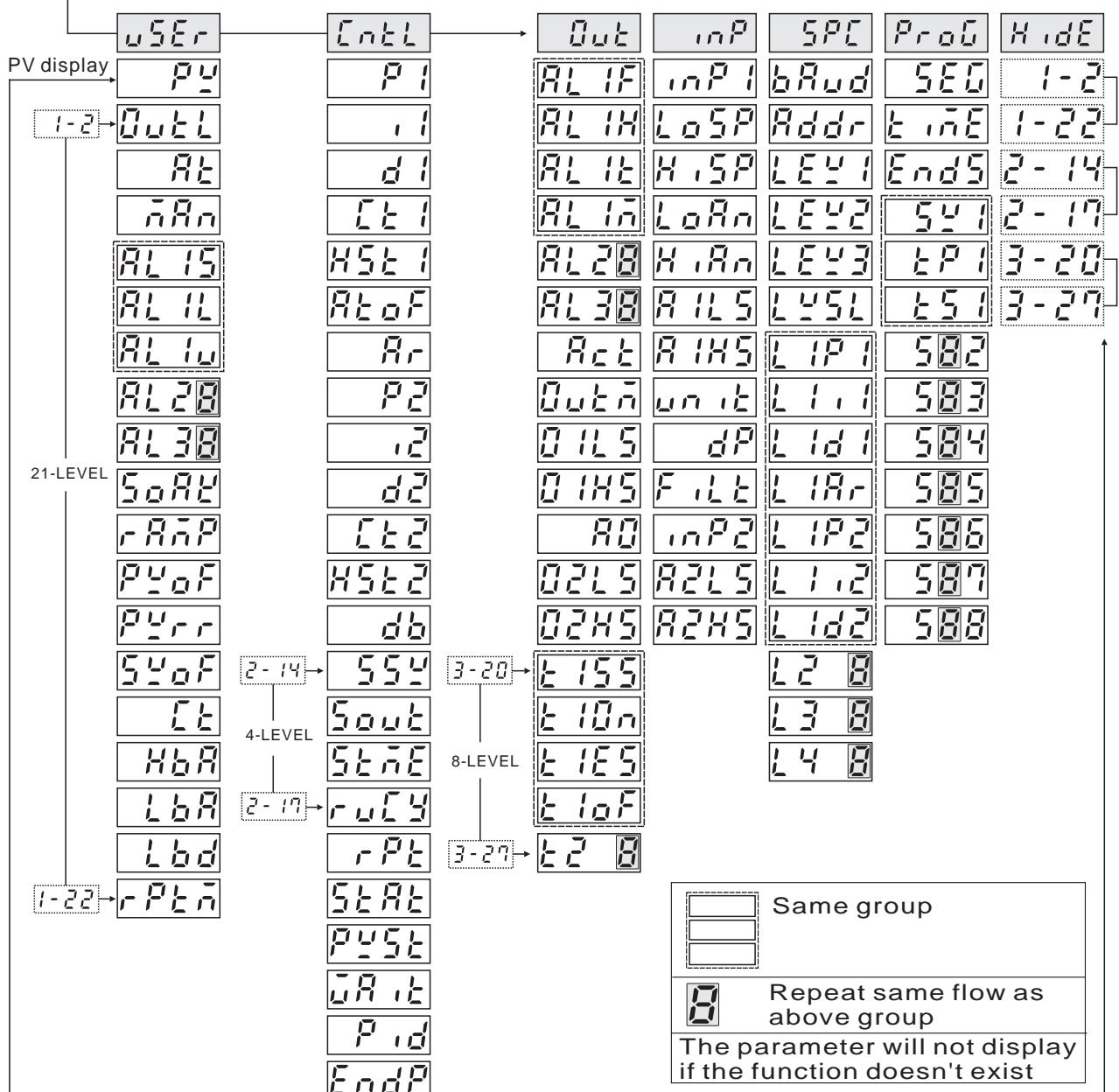
Operation keys (programmable mode only)

These keys are only operated in PV/SV initial window	
↑ 3SEC Run	PRG lights, RP or SK flashes The executing segment lamp lights
↓ 3SEC Pause	PRG, RP and SK light The executing segment lamp lights
↑ + F/S Jump	Jump to the next segment, press ↑ first
↓ + F/S Stop	Turn off all lamps which used for programmable mode, press ↓ first
Refer to arrow ↗ When PRG Lights (No PRG light in MC-5438)	

Window checks display after turning on power



LEVEL Parameter flow chart

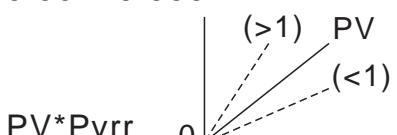


Parameter	DESCRIPTION	RANGE	Initial value
Pv	Process value	LoSP~HiSP	
Sv	Set value	LoSP~HiSP	0.0

USER ▼

OutL	Output percentage	0.0~100.0%	0.0
At	Auto tuning	No / yes	no
Man	Manual mode	Man1 =power failure memory Man2 =no memory No =non	no
AL1S	Alarm 1 set value	If ALIF set at 1 or 2 range=-200~200 If ALIF set at 3 or 4 range=LoSP~HiSP If ALIF set at 10 range =1-8 segment ending	10.0
AL1L	Alarm 1 lower set value	0~200	10.0
AL1u	Alarm 1 upper set value	0~200	10.0

AL2S AL3S For operating functions refer to the above descriptions

SoAK	SoAK	Perform only when ALM1 set at 8 or 9	0.00~99.59 (h.m)	0.00
rAmP	rAmP	Ramp	0.0~200.0/m	0.0
PvoF	PvoF	Pv offset	-200~200	0.0
Pvrr	Pvrr	Pv ratio	0.001~9.999  PV*Pvrr	1.000
SvoF	SvoF	Sv offset	-200~200	0.0
Ct	Ct	Current transformer monitor	0.0~100.0A	
HbA	HbA	Heater break alarm time	0.1~100.0A	0.1
LbA	LbA	Control loop break alarm time	0.1~200.0 min	8.0
Lbd	Lbd	LBA dead band	0.0~200.0	0.0
rPtm	rPtm	Repeat times monitor	1~1000	

Parameter	DESCRIPTION	RANGE	Initial value
ContL			
P1 P1	Output 1 proportional band	0.0~3000	30.0
i1 i1	Output 1 integral time	0~3600	240
d1 d1	Output 1 derivative time	0~900	60
Ct1 Ct1	Output 1 cyclic time	0~150	15
HSt1 HSt1	Output 1 hysteresis	0.0~200.0	0.0
AtoF AtoF	At offset	-200~200	0.0
Ar Ar	Anti-reset windup	0~100.0% SV-P1 x Ar	100.0
P2 P2	Output 2 proportional band	0.0~3000	30.0
i2 i2	Output 2 integral time	0~3600	240
d2 d2	Output 2 derivative time	0~900	60
Ct2 Ct2	Output 2 cyclic time	0~150	15
HSt2 HSt2	Output 2 hysteresis	0.0~200.0	0.0
db db	Dead band/overlap	-200.0~200.0 100% 200.0	0.0
SSv SSv	Soft start set value	0.0~200.0	120.0
Sout Sout	Soft start output percentage	0.0~100.0%	30.0
StmE StmE	Soft start failed time	0~10 min	10
ruCy ruCy	Motor valve cyclic time	1~150 secretary	5
rPt rPt	Program executing times	1~1000	1
StAt StAt	Start mode selection	CoLd = manual rSET= start after power ON Hot= start from memory of power failure	CoLd
PvSt PvSt	Start point selection	RSEt = start from 0 Pv = start from PV	rSEt
wAit wAit	Wait value in program	0.0~200.0	0.0
Pid Pid	PID/Level PID selection	Pid =Pid Lpid =Level Pid	Pid
EndP EndP	Selects control when program ended	Cont=Continue StoP =One program only	StoP

Parameter	DESCRIPTION	RANGE	Initial value
Out ▼			
AL1F AL1F	Alarm 1 action function	0~12 (see Fig 1)	1
AL1H AL1H	Alarm 1 hysteresis	0.0~200.0	0.0
AL1t AL1t	Alarm 1 in program mode on time	0.00~99.59 (h · m)	0.00
AL1m AL1m	Alarm 1 special mode selection	(see Fig 2)	0
For operating functions refer to the above descriptions Different function see(1),(2),(3)			
AL2F AL2F	(1)AL2M Alarm 2 special mode selection (See Fig 2) 0~7		
	(2)AL3F Alarm 3 action function (See Fig 1) 0~11		
AL3F AI3F	(3)AL3M Alarm 3 special mode selection (see Fig 2) 0~7		
Act Act	Control action selection	CooL / HEAt	HEAt
Outm Outm	Output mode selection	(see Fig 3)	1
O1LS O1LS	Output 1 scale low	0.0~100.0%	17.6
O1HS O1HS	Output 1 scale high	0.0~100.0%	96.0
AO AO	Analog output selection	Pv=transmit PV Sv=transmit SV dEv=transmit (PV-SV) Mv=transmit output percentage	Pv
O2LS O2LS	Output 2 scale low	0.0~100.0%	17.6
O2HS O2HS	Output 2 scale high	0.0~100.0%	96.0
t1SS t1SS	Time signal 1 start segment setting	1~8	1
t1On t1On	Time signal 1 on time setting	0.00~99.59 (h · m)	0.01
t1ES t1ES	Time signal 1 end segment setting	1~8	1
t1oF T1oF	Time signal 1 off time setting	0.00~99.59 (h · m)	0.01
t2SS t2SS	For operating functions refer to the above descriptions		

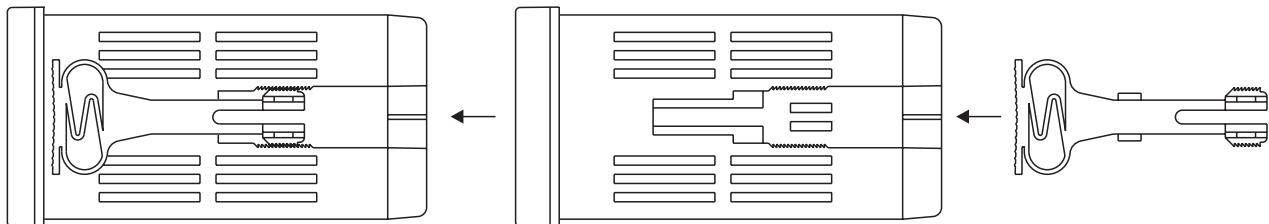
Parameter	DESCRIPTION	RANGE	Initial value
inP ▼			
<i>inP1</i>	inP1 Input 1 selection	(see Fig 4)	K2
<i>LoSP</i>	LoSP Low setting limit	LOSP~HISP	0.0
<i>HiSP</i>	HiSP High setting limit	LOSP~HISP	400.0
<i>LoAn</i>	LoAn Analog input range low	-1999~9999	0.0
<i>HiAn</i>	HiAn Analog input range high	-1999~9999	100.0
<i>A1LS</i>	A1LS Analog input 1 scale low	0~FFFF	
<i>A1HS</i>	A1HS Analog input 1 scale high	0~FFFF	
<i>unit</i>	Unit selection	°C/°F/non	°C
<i>dP</i>	dP Decimal point	0/0.0/0.00/0.000	0.0
<i>FiL</i> <i>t</i>	FiLt Digital filter	0.001~ 1.000 Non = no function Ct = use for heater break alarm rmSV= use for remote SV	0.900 non
<i>inP2</i>	inP2 Input 2 selection		
<i>A2LS</i>	A2LS Analog input 2 scale low	0~FFFF	
<i>A2HS</i>	A2HS Analog input 2 scale high	0~FFFF	
SPC ▼			
<i>bAud</i>	bAud Baud rate	2.4K / 4.8K / 9.6K 19.2K / 38.4K	9.6K
<i>Addr</i>	Addr Address	0~31	0
<i>Lev1</i>	Lev1 PID range(act only when level PID is selected)	LoSP~HiSP	400
<i>Lev2</i>	Lev2 PID range(act only when level PID is selected)	LoSP~HiSP	400
<i>Lev3</i>	Lev3 PID range(act only when level PID is selected)	LoSP~HiSP	400
<i>LvSL</i>	LvSL Leve is selection	1~4	1
<i>L1P1</i>	L1P1 Output 1 proportional band for level 1	0.0~3000	30.0
<i>L1i1</i>	L1i1 Output 1 integral time for level1	0~3600	240
<i>L1d1</i>	L1d1 Output 1 derivative time for level1	0~900	60
<i>L1Ar</i>	L1Ar Anti-reset windup for level1	0.0~100.0%	100.0
<i>L1P2</i>	L1P2 Output 2 proportional band for level 1	0.0~3000	30.0
<i>L1i2</i>	L1i2 Output 2 integral time for level1	0~3600	240
<i>L1d2</i>	L1d2 Output 2 derivative time for level 1	0~900	60
<i>L2P</i> ~ 4	The same as level 1		

Parameter	DESCRIPTION	RANGE	Initial value
Prog ▼			
SEG	SEG	Program segment monitor	1~8
Time	TimE	Program countdown monitor	
EndS	EndS	Program segment end setting	1~8
Sv1	Sv1	Sv in segment 1	LoSP~HiSP
tP1	tP1	Program time in segment 1	0.00~99.59 (H.M)
tS1	tS1	Soak time in segment 1	0.00~99.59 (H.M)
Sv2~8 The same as segment 1			

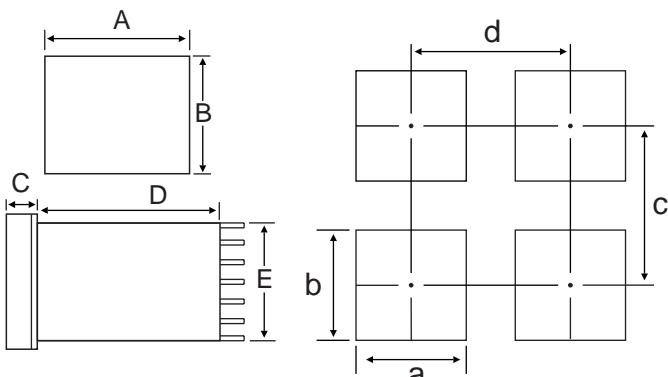
H. idE ▼

1-2~1-22	Parameter shows with respect to this position	non~t2of	
2-14~2-17	Parameter shows with respect to this position	non~t2of	
3-20~3-27	Parameter shows with respect to this position	non~t2of	

Mounting procedures



Dimension



Type	A	B	C	D	E	a	b	c	d
MC-5838	96	96	10.5	83	90	91 ^{+0.5} ₋₀	91 ^{+0.5} ₋₀	120	120
MC-5738	72	72	10.5	83	67	68 ^{+0.5} ₋₀	68 ^{+0.5} ₋₀	100	100
MC-5638	96	48	10.5	83	43	91 ^{+0.5} ₋₀	46 ^{+0.5} ₋₀	70	120
MC-5538	48	96	10.5	83	90	46 ^{+0.5} ₋₀	91 ^{+0.5} ₋₀	120	70
MC-5438	48	48	10.5	83	45	46 ^{+0.5} ₋₀	46 ^{+0.5} ₋₀	70	70

Fig 1. Alarm Mode Selection
(used in parameter AL1F, AL2F, AL3F)

AL1F	AL2F	AL3F	Alarm function selection	
0	0	0	No alarm	
1	1	1	Deviation high alarm	
2	2	2	Deviation low alarm	
3	3	3	Absolute high alarm	
4	4	4	Absolute low alarm	
5	5	5	Deviation high/low alarm	
6	6	6	Band alarm	
7	7	7	System failure alarm (when error information happen)	
8	8	8	Loop break alarm	
9	9	9	Heater break alarm	
10	10	10	Segment ending alarm in program control	
11	11	11	Program ending alarm in program control	
12	12		Time signal alarm	
13	13		Program running alarm in program control	

Fig 2. special alarm function selection
(used in parameter AL1M, AL2M, AL3M)

AL1M	AL2M	AL3M	Special alarm mode selection
0	0	0	Normal
1	1	1	Alarm with normal-close contact
2	2	2	Latch
3	3	3	Alarm with normal-close contact and latch
4	4	4	Alarm with inhibit
5	5	5	Alarm with inhibit and normal-close contact
6	6	6	Alarm with inhibit and latch
7	7	7	Alarm with inhibit, normal-close contact and latch
8			Alarm with on-delay timer
9			Alarm with on-delay timer but normal-close contact
10			Alarm with soaking timer
11			Alarm with soaking timer but normal-close contact

Fig 3. output mode selection
(used in parameter OUTM)

0	Non
1	Single output
2	Dual output
3	Motor value control output "a" contact
4	Motor value control output b contact
5	Single output with transmitter
6	Single output with soft start
7	Single output with transmitter and soft start
8	Program control
9	Program control with transmitter

※NO.2~9 need to be ordered

External terminal

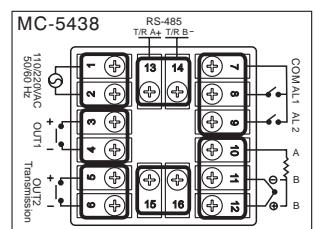
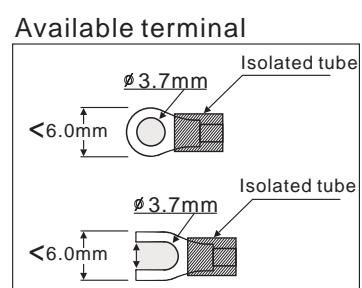
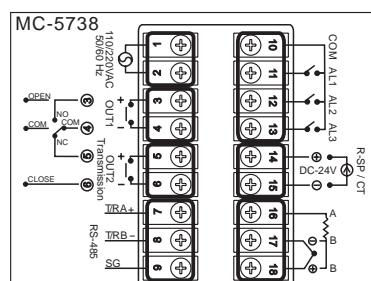
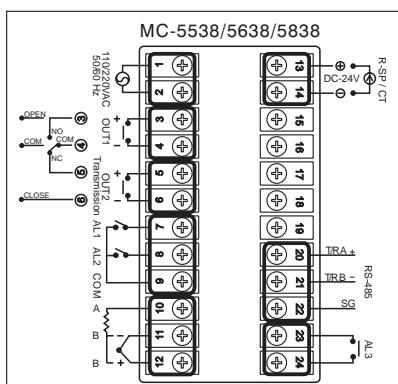


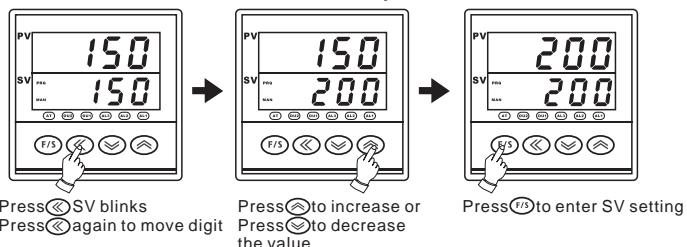
Fig 4. (used in parameter InP1)
input & temperature ranges selection

TYPE	°C	°F
K1	0~200	32~392
K2	0~400	32~752
K3	0~800	32~1472
K4	0~1000	32~1832
K5	0~1200	32~2192
j1	0~200	32~392
j2	0~400	32~752
j3	0~800	32~1472
j4	0~1000	32~1832
j5	0~1200	32~2192
t1	-50~50	-58~122
t2	-100~100	-148~212
t3	-200~400	-328~752
r	0~1700	32~3092
E	0~1000	32~1832
S	0~1700	32~3092
b	0~1800	32~3272
n	-200~1300	-328~2372
Pt1	-50~50	-58~122
Pt2	0~100	32~212
Pt3	0~200	32~392
Pt4	0~400	32~752
Pt5	-200~600	-328~1112
jPt	-200~500	-328~932
Lin	-1999~9999	

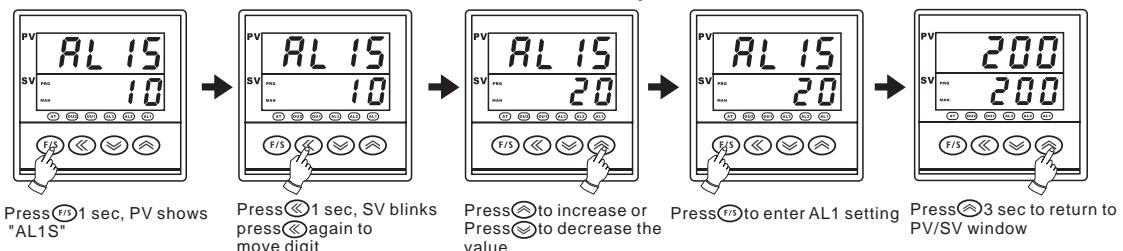
Fig 5.Error information

Display	description
in1E	Input 1 error
RdCF	A/D converter failed
CJCE	Cold junction compensation failed
in2E	Input 2 error
PvBlinks	PV exceeds set Ranges
rRnf	Ram failed
intF	Interface failed
AutF	Auto tuning failed

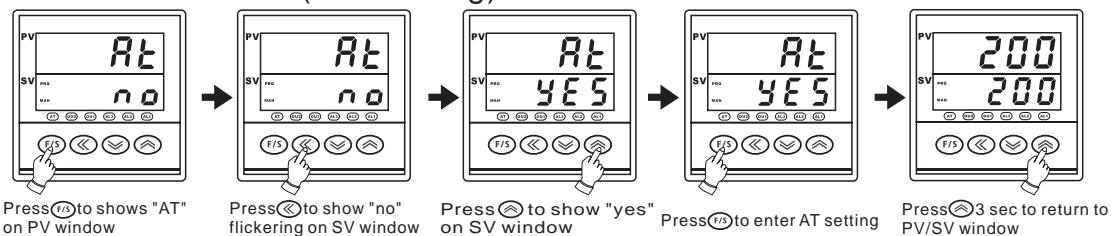
A How to set "SV" example: SV set at 200 C°



B How to set "AL1S,AL2S,AL3S" example: alarm 1 set at 20 C°

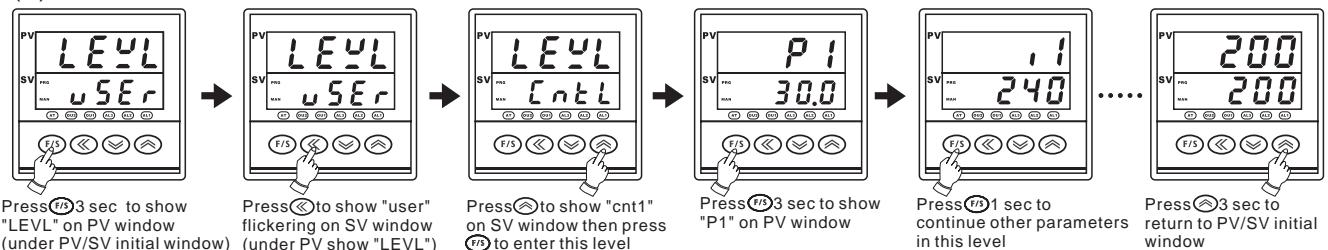


C How to set "AT" (auto tuning)

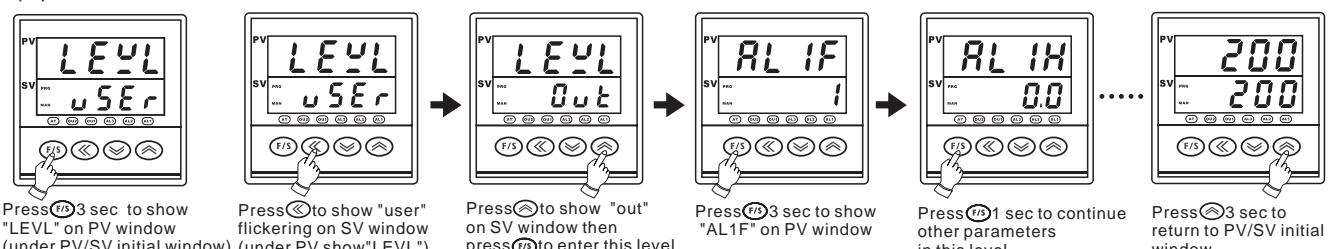


D How to enter different "level" for setting parameter

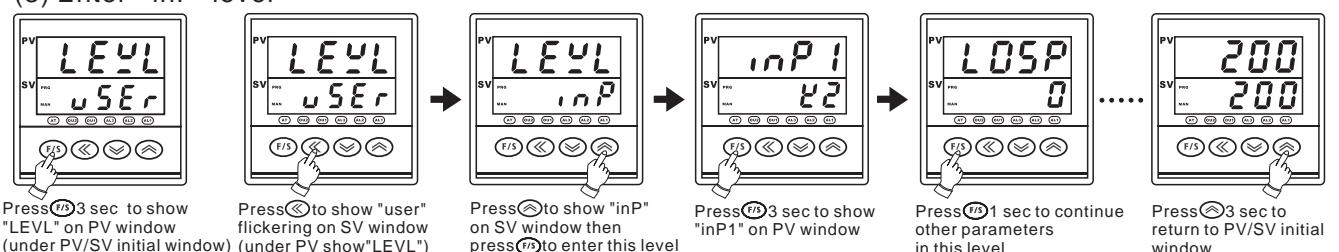
(1) Enter "CntL" level



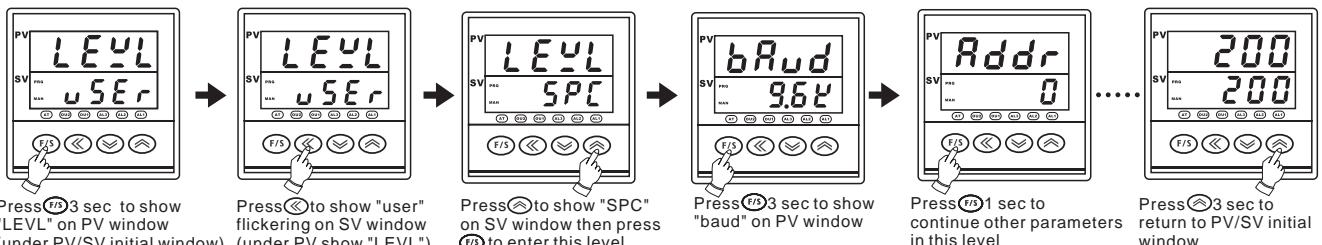
(2) Enter "Out" level



(3) Enter "inP" level

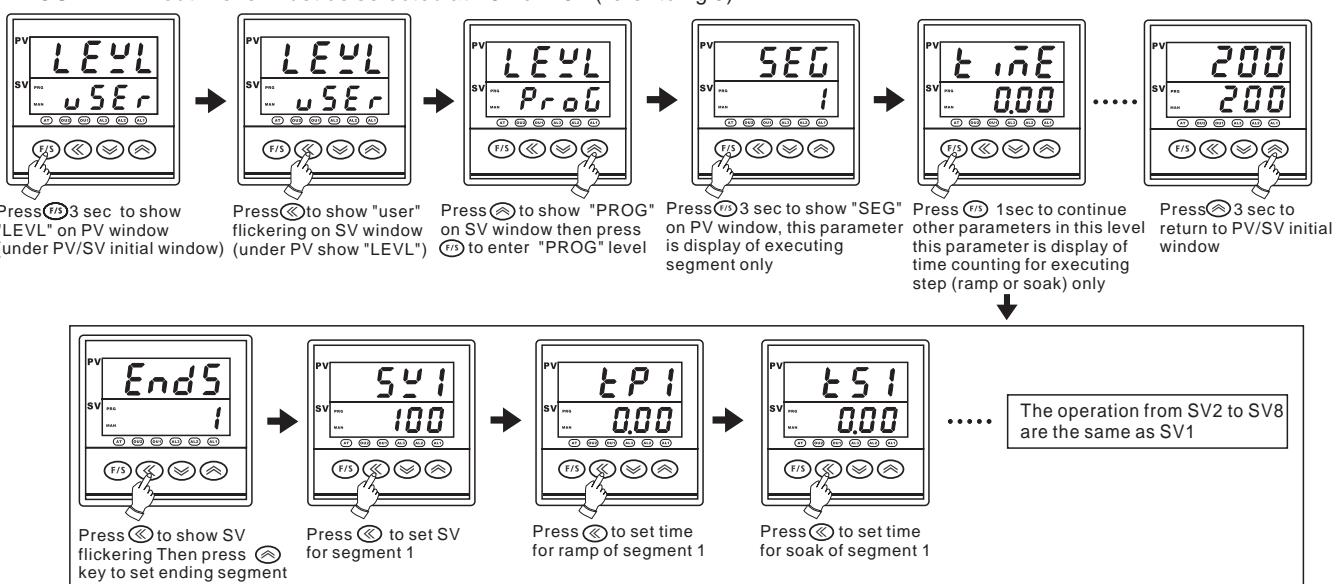


(4) Enter "Spc" level



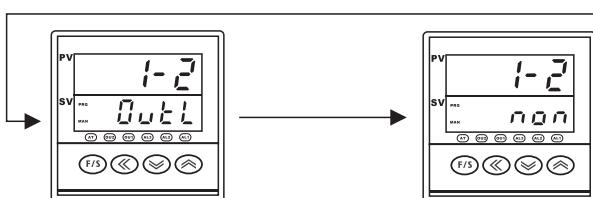
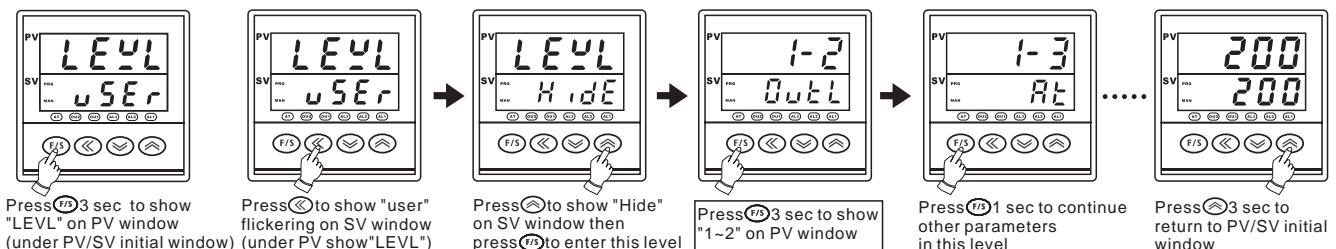
(5) Enter program level

* "OUTM" in "out" level must be selected at "8" or "9" (refer to fig 3)



(6) Enter "Hide" level

In this level, the user can arrange parameter order or hiding from NO. 1-2 to 1-22, 2-14 to 2-17 and 3-20 to 3-27
(please refer to level parameter flow chart in page 1), but same parameter can not be arranged in 2 positions in the same time, for example you want to arrange "OUTL" to 1-3 you need to cancel it in 1-2 first. When you want to cancel or hide it you need to choice "non" on the "SV"

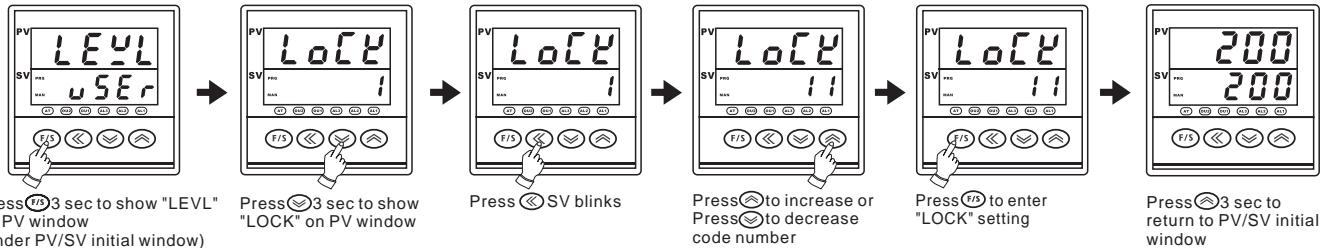


PRESS F2 1 SEC to show "OUTL" flickering then press F2 key to "non" for hiding and canceling or press F1 key to choice other parameters.

If you choice "non" in 1-2 and press F1 to enter then 1-2 will not display anything but if you choice other parameter in 1-2, it will display which parameter.

The operation in 1-2 to 1-22, 2-14 to 2-17 and 3-20 to 3-27 all are the same.

E How to set "LoCK" function



Code number for Lock function

[0000]	all parameters are locked except PV
[1001]	all parameters are locked except SV
[0111]	open "USER" level and above
[0122]	open "CNTL" level and above
[1111]	open "OUT" level (Except OUTM) and above
[0222]	open "INP" level and above
[1100]	open "SPC" level and above
[2200]	open "PROG" level and above
[1112]	open "HIDE" level and above
[1234]	open "USER" and "PROG" level only

F. How to modify input

This series controller provides free input for T/C and RTD,
it doesn't need to modify hardware except analog input.

1. Analog input hardware modification

(Refer to S1~S8 on PC board back)

S1 & S2 are shorted with COM. originally,
so it needs to open S1 or S1& S2 and to short some pads as drawing.

INPUT	S1	S2	S3	S4	S5	S6	S7	S8
TC/RTD	○	○	✗	✗	✗	✗	✗	✗
0~20MA	✗	○	✗	✗	○	✗	✗	✗
4~20MA	✗	○	✗	✗	○	✗	✗	✗
0~100MV	✗	✗	○	✗	✗	○	✗	✗
0~1V	✗	✗	✗	○	✗	○	✗	✗
0~5V	✗	✗	✗	✗	✗	○	✗	○
1~5V	✗	✗	✗	✗	✗	○	○	✗
0~10V	✗	✗	✗	✗	✗	○	✗	○

[○] short [✗] open

2. Analog input software modification

- ※Select "Lin" in "inpl" parameter
- ※Set "LoAn" in "inp" level to lowest range
- ※Set "HiAn" in "inp" level to highest range

3. Analog input calibration

- ※Enter "A1LS" parameter in "inp" level
- ※Provide signal for lowest range and wait for 3 sec then keep pressing  key
- ※Enter "A1HS" parameter in "inp" level
- ※Provide signal for highest range and wait for 3 sec then keep pressing  key
- ※Return to PV/SV initial window and provide signal for lowest range again then check if PV equals to LoAn
- ※Provide signal for highest range again then check if PV equals to HiAn
If it is not accuracy after calibrating, please repeat above procedure again

SPECIFICATIONS

PV Input	Type of Input	TC (K,J,T,R,E,S,B,N) RTD (Pt100, JPt100) Linear(1-5V, 4-20mA)
	Input Sampling Time	300 ms
Indication	PV/SV Indication	4-digit
	Constant Value Storage System	Non-volatile memory (E ² PROM)
Control Mode	Proportional Band (P)	0.0~3000
	Integral Time (I)	0~3600
	Derivative Time (D)	0~900
	Cycle Time	0~150
	Dead Band	0.0~200.0
Output	Relay Output Relay	Contact, SPDT 3A/240VAC
	Voltage Output	Voltage Pulse
	Linear Output	4~20mA, 1-5V ,
	Motor Control Output	Open loop motor valve
Alarm	Channel	3 Channels (Optional)
Communication	Type of Communication	RS-232, RS-485
General Specifications	Power Supply Voltage & Frequency	AC 90~260V, 50/60Hz
	Power Consumption	<3.5VA
	Ambient Temperature	-10°C ~ 55°C
	Ambient Humidity	0~80% RH

ORDERING INFORMATION

A B C D E F G
M C - **5438** - **101** - **000**

A: Type (Dimension) MC-5438 = 48x48mm (DIN 1/16), MC-5538 = 48x96mm (DIN 1/8), MC-5638 = 96x48mm (DIN 1/8), MC-5838 = 96x96mm (DIN 1/4), MC-5738 = 72x72mm	B: Output 1 0=NONE 1=Relay, contact, SPDT 3A/240VAC 2=Volt, voltage pulse, 20VDC/20mA 3=mA Current, 4~20mA 4=Open loop circuit servo motor control A=0~5V B=0~10V C=1~5V D=2~10V	E: Transmission 0=None 1=4~20mA (Adjustable) 2=0~20mA (Adjustable) A=0~5V B=0~10V C=1~5V D=2~10V
C: Output 2 0=NONE 1=Relay, contact, SPDT 3A/240VAC 2=Volt, voltage pulse, 20VDC/20mA 3=mA Current, 4~20mA A=0~5V B=0~10V C=1~5V D=2~10V	F: Input 2 0=None 1=4~20mA remote set point 2=0~20mA remote set point 3=CT for heater break alarm A=0~5V remote set point B=0~10V remote set point C=1~5V remote set point D=2~10V remote set point	
D: Alarm 0 = NONE 1 = Alarm x 1 2 = Alarm x 2 3 = Alarm x 3	G: Communication 0 = None 1 = RS-232 2 = RS-485	